

Adaptive Backstepping Control Of Uncertain Systems Nonsmooth Nonlinearities Interactions Or Time Variations Lecture Notes In Control And Information Sciences

If you ally dependence such a referred **Adaptive Backstepping Control Of Uncertain Systems Nonsmooth Nonlinearities Interactions Or Time Variations Lecture Notes In Control And Information Sciences** books that will have the funds for you worth, get the totally best seller from us currently from several preferred authors. If you want to droll books, lots of novels, tale, jokes, and more fictions collections are plus launched, from best seller to one of the most current released.

You may not be perplexed to enjoy all ebook collections **Adaptive Backstepping Control Of Uncertain Systems Nonsmooth Nonlinearities Interactions Or Time Variations Lecture Notes In Control And Information Sciences** that we will agreed offer. It is not nearly the costs. Its very nearly what you infatuation currently. This **Adaptive Backstepping Control Of Uncertain Systems Nonsmooth Nonlinearities Interactions Or Time Variations Lecture Notes In Control And Information Sciences**, as one of the most committed sellers here will agreed be in the

course of the best options to review.

Neural Information

Processing - Derong Liu

2017-11-07

The six volume set LNCS 10634, LNCS 10635, LNCS 10636, LNCS 10637, LNCS 10638, and LNCS 10639 constitutes the proceedings of the 24rd International Conference on Neural Information Processing, ICONIP 2017, held in Guangzhou, China, in November 2017. The 563 full papers presented were carefully reviewed and selected from 856 submissions. The 6 volumes are organized in topical sections on Machine Learning, Reinforcement Learning, Big Data Analysis, Deep Learning, Brain-Computer Interface, Computational Finance, Computer Vision, Neurodynamics, Sensory Perception and Decision Making, Computational Intelligence, Neural Data Analysis, Biomedical Engineering, Emotion and

Bayesian Networks, Data Mining, Time-Series Analysis, Social Networks, Bioinformatics, Information Security and Social Cognition, Robotics and Control, Pattern Recognition, Neuromorphic Hardware and Speech Processing.

Model Free Adaptive Control

- Zhongsheng Hou 2013-09-24

Model Free Adaptive Control: Theory and Applications summarizes theory and applications of model-free adaptive control (MFAC). MFAC is a novel adaptive control method for the unknown discrete-time nonlinear systems with time-varying parameters and time-varying structure, and the design and analysis of MFAC merely depend on the measured input and output data of the controlled plant, which makes it more applicable for many practical plants. This book covers new concepts, including pseudo partial derivative, pseudo gradient,

pseudo Jacobian matrix, and generalized Lipschitz conditions, etc.; dynamic linearization approaches for nonlinear systems, such as compact-form dynamic linearization, partial-form dynamic linearization, and full-form dynamic linearization; a series of control system design methods, including MFAC prototype, model-free adaptive predictive control, model-free adaptive iterative learning control, and the corresponding stability analysis and typical applications in practice. In addition, some other important issues related to MFAC are also discussed. They are the MFAC for complex connected systems, the modularized controller designs between MFAC and other control methods, the robustness of MFAC, and the symmetric similarity for adaptive control system design. The book is written for researchers who are interested in control theory and control engineering, senior undergraduates and graduated students in engineering and applied sciences, as well as

professional engineers in process control.

Control Design Techniques in Power Electronics Devices - Hebertt J. Sira-Ramirez
2006-09-07

This book deals specifically with control theories relevant to the design of control units for switched power electronics devices, for the most part represented by DC-DC converters and supplies, by rectifiers of different kinds and by inverters with varying topologies. The theoretical methods for designing controllers in linear and nonlinear systems are accompanied by multiple case studies and examples showing their application in the emerging field of power electronics.

Advances in Neural Networks - ISNN 2019 - Huchuan Lu 2019-06-26

This two-volume set LNCS 11554 and 11555 constitutes the refereed proceedings of the 16th International Symposium on Neural Networks, ISNN 2019, held in Moscow, Russia, in July 2019. The 111 papers

presented in the two volumes were carefully reviewed and selected from numerous submissions. The papers were organized in topical sections named: Learning System, Graph Model, and Adversarial Learning; Time Series Analysis, Dynamic Prediction, and Uncertain Estimation; Model Optimization, Bayesian Learning, and Clustering; Game Theory, Stability Analysis, and Control Method; Signal Processing, Industrial Application, and Data Generation; Image Recognition, Scene Understanding, and Video Analysis; Bio-signal, Biomedical Engineering, and Hardware.

Robot Motion Planning - Jean-Claude Latombe 2012-12-06

One of the ultimate goals in Robotics is to create autonomous robots. Such robots will accept high-level descriptions of tasks and will execute them without further human intervention. The input descriptions will specify what the user wants done rather than how to do it. The robots will be any kind of versatile

mechanical device equipped with actuators and sensors under the control of a computing system. Making progress toward autonomous robots is of major practical interest in a wide variety of application domains including manufacturing, construction, waste management, space exploration, undersea work, assistance for the disabled, and medical surgery. It is also of great technical interest, especially for Computer Science, because it raises challenging and rich computational issues from which new concepts of broad usefulness are likely to emerge. Developing the technologies necessary for autonomous robots is a formidable undertaking with deep interweaved ramifications in automated reasoning, perception and control. It raises many important problems. One of them - motion planning - is the central theme of this book. It can be loosely stated as follows: How can a robot decide what motions to perform in order to achieve

goal arrangements of physical objects? This capability is eminently necessary since, by definition, a robot accomplishes tasks by moving in the real world. The minimum one would expect from an autonomous robot is the ability to plan its own motions.

Integration of Fuzzy Logic and Chaos Theory - Zhong Li
2008-07-21

The 1960s were perhaps a decade of confusion, when scientists faced difficulties in dealing with imprecise information and complex dynamics. A new set theory and then an infinite-valued logic of Lotfi A. Zadeh were so confusing that they were called fuzzy set theory and fuzzy logic; a deterministic system found by E. N. Lorenz to have random behaviours was so unusual that it was lately named a chaotic system. Just like irrational and imaginary numbers, negative energy, anti-matter, etc., fuzzy logic and chaos were gradually and eventually accepted by many, if not all, scientists and engineers as fundamental

concepts, theories, as well as technologies. In particular, fuzzy systems technology has achieved its maturity with widespread applications in many industrial, commercial, and technical fields, ranging from control, automation, and artificial intelligence to image/signal processing, pattern recognition, and electronic commerce. Chaos, on the other hand, was considered one of the great monumental discoveries of the twentieth century together with the theory of relativity and quantum mechanics. As a very special nonlinear dynamical phenomenon, chaos has reached its current outstanding status from being merely a scientist's curiosity in the mid-1960s to an applicable technology in the late 1990s. Finding the intrinsic relation between fuzzy logic and chaos theory is certainly of significant interest and of potential importance. The past 20 years have indeed witnessed some serious explorations of the interactions between

fuzzy logic and chaos theory, leading to such research topics as fuzzy modeling of chaotic systems using Takagi-Sugeno models, linguistic descriptions of chaotic systems, fuzzy control of chaos, and a combination of fuzzy control technology and chaos theory for various engineering practices.

Disturbance Observer-Based Control - Shihua Li 2016-04-19

Due to its abilities to compensate disturbances and uncertainties, disturbance observer based control (DOBC) is regarded as one of the most promising approaches for disturbance-attenuation. One of the first books on DOBC, Disturbance Observer Based Control: Methods and Applications presents novel theory results as well as best practices for applica

Nonlinear Industrial Control Systems - Michael J. Grimble 2020-05-19

Nonlinear Industrial Control Systems presents a range of mostly optimisation-based methods for severely nonlinear systems; it discusses feedforward and feedback

control and tracking control systems design. The plant models and design algorithms are provided in a MATLAB® toolbox that enable both academic examples and industrial application studies to be repeated and evaluated, taking into account practical application and implementation problems. The text makes nonlinear control theory accessible to readers having only a background in linear systems, and concentrates on real applications of nonlinear control. It covers: different ways of modelling nonlinear systems including state space, polynomial-based, linear parameter varying, state-dependent and hybrid; design techniques for nonlinear optimal control including generalised-minimum-variance, model predictive control, quadratic-Gaussian, factorised and H^∞ design methods; design philosophies that are suitable for aerospace, automotive, marine, process-control, energy systems, robotics, servo systems and manufacturing; steps in design

procedures that are illustrated in design studies to define cost-functions and cope with problems such as disturbance rejection, uncertainties and integral wind-up; and baseline non-optimal control techniques such as nonlinear Smith predictors, feedback linearization, sliding mode control and nonlinear PID. *Nonlinear Industrial Control Systems* is valuable to engineers in industry dealing with actual nonlinear systems. It provides students with a comprehensive range of techniques and examples for solving real nonlinear control design problems.

[Bifurcation Control](#) - Guanrong Chen 2003-08-26

Bifurcation control refers to the task of designing a controller that can modify the bifurcation properties of a given nonlinear system, so as to achieve some desirable dynamical behaviors. There exists no similar control theory-oriented book available in the market that is devoted to the subject of bifurcation control, written by control engineers

for control engineers. World-renowned leading experts in the field provide their state-of-the-art survey about the extensive research that has been done over the last few years in this subject. The book is not only aimed at active researchers in the field of bifurcation control and its applications, but also at a general audience in related fields.

Modern Sliding Mode Control Theory - Giorgio Bartolini 2008-04-05

This concise book covers modern sliding mode control theory. The authors identify key contributions defining the theoretical and applicative state-of-the-art of the sliding mode control theory and the most promising trends of the ongoing research activities.

Adaptive Control of Nonsmooth Dynamic Systems - Gang Tao 2001-09-26

Many of the non-smooth, nonlinear phenomena covered in this well-balanced book are of vital importance in almost any field of engineering.

Contributors from all over the

world ensure that no one area's slant on the subjects predominates.

Proceedings of the 4th International Conference on Electrical Engineering and Control Applications - Sofiane Bououden 2020-09-29

This book gathers papers presented during the 4th International Conference on Electrical Engineering and Control Applications. It covers new control system models, troubleshooting tips and complex system requirements, such as increased speed, precision and remote capabilities. Additionally, the papers discuss not only the engineering aspects of signal processing and various practical issues in the broad field of information transmission, but also novel technologies for communication networks and modern antenna design. This book is intended for researchers, engineers and advanced postgraduate students in the fields of control and electrical engineering, computer science and signal

processing, as well as mechanical and chemical engineering.

Robust Control and Linear Parameter Varying Approaches

- Olivier Sename 2013-02-01

Vehicles are complex systems (non-linear, multi-variable) where the abundance of embedded controllers should ensure better security. This book aims at emphasizing the interest and potential of Linear Parameter Varying methods within the framework of vehicle dynamics, e.g. proposed control-oriented model, complex enough to handle some system non linearities but still simple for control or observer design, take into account the adaptability of the vehicle's response to driving situations, to the driver request and/or to the road solicitations, manage interactions between various actuators to optimize the dynamic behavior of vehicles. This book results from the 32th International Summer School in Automatic that held in Grenoble, France, in September 2011, where recent

methods (based on robust control and LPV technics), then applied to the control of vehicle dynamics, have been presented. After some theoretical background and a view on some recent works on LPV approaches (for modelling, analysis, control, observation and diagnosis), the main emphasis is put on road vehicles but some illustrations are concerned with railway, aerospace and underwater vehicles. The main objective of the book is to demonstrate the value of this approach for controlling the dynamic behavior of vehicles. It presents, in a rm way, background and new results on LPV methods and their application to vehicle dynamics.

Control of Nonlinear and Hybrid Process Systems -

Panagiotis D. Christofides
2005-10-04

This monograph provides insight and fundamental understanding into the feedback control of nonlinear and hybrid process systems. It presents state-of-the-art

methods for the synthesis of nonlinear feedback controllers for nonlinear and hybrid systems with uncertainty, constraints and time-delays with numerous applications, especially to chemical processes. It covers both state feedback and output feedback (including state estimator design) controller designs. Control of Nonlinear and Hybrid Process Systems includes numerous comments and remarks providing insight and fundamental understanding into the feedback control of nonlinear and hybrid systems, as well as applications that demonstrate the implementation and effectiveness of the presented control methods. The book includes many detailed examples which can be easily modified by a control engineer to be tailored to a specific application. This book is useful for researchers in control systems theory, graduate students pursuing their degree in control systems and control engineers.

Control Technologies for

Emerging Micro and Nanoscale Systems -

Evangelos Eleftheriou
2011-07-15

This book comprises a selection of the presentations made at the “Workshop on Dynamics and Control of Micro and Nanoscale Systems” held at IBM Research – Zurich, Switzerland, on the 10th and 11th of December 2009. The aim of the workshop was to bring together some of the leading researchers in the field of dynamics and control of micro- and nanoscale systems. It proved an excellent forum for discussing new ideas and approaches.

Hybrid Technologies for Power Generation -

Massimiliano Lo Faro
2021-10-30

Hybrid Technologies for Power Generation addresses the topics related to hybrid technologies by coupling conventional thermal engines with novel technologies, including fuel cells, batteries, thermal storage and electrolysis, and reporting on the most recent advances

concerning transport and stationary applications. Potential operating schemes of hybrid power generation systems are covered, highlighting possible combinations of technology and guideline selection according to the energy demands of end-users. Going beyond state-of-the-art technological developments for processes, devices and systems, this book discusses the environmental impact and existing hurdles of moving from a single device to new approaches for efficient energy generation, transfer, conversion, high-density storage and consumption. By describing the practical viability of novel devices coupled to conventional thermal devices, this book has a decisive impact in energy system research, supporting those in the energy research and engineering communities. Covers detailed thermodynamic requirements for multiple smart technologies included in hybrid systems (i.e., FC, electrolysers, supercapacitors, batteries,

thermal storage, etc.) Features fundamental analysis and modeling to optimize the combination of smart technologies with traditional engines Details protocols for the analysis, operation and requirements of large-scale production

Control of Axially Moving Systems - Keum-Shik Hong
2022-10-21

This book provides a comprehensive guideline on dynamic analysis and vibration control of axially moving systems. First, the mathematical models of various axially moving systems describing the string, beam, belt, and plate models are developed. Accordingly, dynamical issues such as the equilibrium configuration, critical velocity, stability, bifurcation, and further chaotic dynamics are analyzed. Second, this book covers the design of the control schemes based on the hitherto control strategies for axially moving systems: feedback control using the transfer function, variable structure control,

control by regulating the axial velocity, wave cancellation approach, boundary control using the Lyapunov method, adaptive control, and hybrid control methods. Finally, according to the contents discussed in the book, specific aspects are outlined for initiating future research endeavors to be undertaken concerning axially moving systems. This book is useful to graduate students and researchers in industrial sectors such as continuous manufacturing systems, transport systems, power transmission systems, and lifting systems not to mention in academia.

Backstepping Control of Nonlinear Dynamical Systems - Sundarapandian Vaidyanathan 2020-08-15

Backstepping Control of Nonlinear Dynamical Systems addresses both the fundamentals of backstepping control and advances in the field. The latest techniques explored include 'active backstepping control', 'adaptive backstepping

control', 'fuzzy backstepping control' and 'adaptive fuzzy backstepping control'. The reference book provides numerous simulations using MATLAB and circuit design. These illustrate the main results of theory and applications of backstepping control of nonlinear control systems. Backstepping control encompasses varied aspects of mechanical engineering and has many different applications within the field. For example, the book covers aspects related to robot manipulators, aircraft flight control systems, power systems, mechanical systems, biological systems and chaotic systems. This multifaceted view of subject areas means that this useful reference resource will be ideal for a large cross section of the mechanical engineering community. Details the real-world applications of backstepping control Gives an up-to-date insight into the theory, uses and application of backstepping control Bridges the gaps for different fields of engineering, including

mechanical engineering, aeronautical engineering, electrical engineering, communications engineering, robotics and biomedical instrumentation

Advances and Applications in Sliding Mode Control

systems - Ahmad Taher Azar
2014-11-01

This book describes the advances and applications in Sliding mode control (SMC) which is widely used as a powerful method to tackle uncertain nonlinear systems. The book is organized into 21 chapters which have been organised by the editors to reflect the various themes of sliding mode control. The book provides the reader with a broad range of material from first principles up to the current state of the art in the area of SMC and observation presented in a clear, matter-of-fact style. As such it is appropriate for graduate students with a basic knowledge of classical control theory and some knowledge of state-space methods and nonlinear systems. The

resulting design procedures are emphasized using Matlab/Simulink software.

Theory and Practice of Control and Systems - Antonio Tornambè 1998

This volume gathers together all the lectures presented at the 6th IEEE Mediterranean Conference. It focuses on the mathematical aspects in the theory and practice of control and systems, including stability and stabilizability, robust control, adaptive control, robotics and manufacturing; these topics are under intense investigation and development in the engineering and mathematics communities. The volume should have immediate appeal for a large group of engineers and mathematicians who are interested in very abstract as well as very concrete aspects of control and system theory.

Handbook of Marine Craft Hydrodynamics and Motion Control - Thor I. Fossen
2021-04-16

Handbook of MARINE CRAFT HYDRODYNAMICS AND MOTION CONTROL The latest

tools for analysis and design of advanced GNC systems
Handbook of Marine Craft Hydrodynamics and Motion Control is an extensive study of the latest research in hydrodynamics, guidance, navigation, and control systems for marine craft. The text establishes how the implementation of mathematical models and modern control theory can be used for simulation and verification of control systems, decision-support systems, and situational awareness systems. Coverage includes hydrodynamic models for marine craft, models for wind, waves and ocean currents, dynamics and stability of marine craft, advanced guidance principles, sensor fusion, and inertial navigation. This important book includes the latest tools for analysis and design of advanced GNC systems and presents new material on unmanned underwater vehicles, surface craft, and autonomous vehicles. References and examples are included to enable engineers to

analyze existing projects before making their own designs, as well as MATLAB scripts for hands-on software development and testing. Highlights of this Second Edition include: Topical case studies and worked examples demonstrating how you can apply modeling and control design techniques to your own designs A Github repository with MATLAB scripts (MSS toolbox) compatible with the latest software releases from Mathworks New content on mathematical modeling, including models for ships and underwater vehicles, hydrostatics, and control forces and moments New methods for guidance and navigation, including line-of-sight (LOS) guidance laws for path following, sensory systems, model-based navigation systems, and inertial navigation systems This fully revised Second Edition includes innovative research in hydrodynamics and GNC systems for marine craft, from ships to autonomous vehicles operating on the surface and

under water. Handbook of Marine Craft Hydrodynamics and Motion Control is a must-have for students and engineers working with unmanned systems, field robots, autonomous vehicles, and ships. MSS toolbox: <https://github.com/cybergalactic/mss> Lecture notes: <https://www.fossen.biz/wiley> Author's home page: <https://www.fossen.biz> *Road Map for Sliding Mode Control Design* - Vadim Utkin 2020-04-13

This book is devoted to control of finite and infinite dimensional processes with continuous-time and discrete time control, focusing on suppression problems and new methods of adaptation applicable for systems with sliding motions only. Special mathematical methods are needed for all the listed control tasks. These methods are addressed in the initial chapters, with coverage of the definition of the multidimensional sliding modes, the derivation of the differential equations of those

motions, and the existence conditions. Subsequent chapters discuss various areas of further research. The book reflects the consensus view of the authors regarding the current status of SMC theory. It is addressed to a broad spectrum of engineers and theoreticians working in diverse areas of control theory and applications. It is well suited for use in graduate and postgraduate courses in such university programs as Electrical Engineering, Control of Nonlinear Systems, and Mechanical Engineering.

Uncertainty in Complex Networked Systems - Tamer Başar 2018-12-14

The chapters in this volume, and the volume itself, celebrate the life and research of Roberto Tempo, a leader in the study of complex networked systems, their analysis and control under uncertainty, and robust designs. Contributors include authorities on uncertainty in systems, robustness, networked and network systems, social networks, distributed and

randomized algorithms, and multi-agent systems—all fields that Roberto Tempo made vital contributions to. Additionally, at least one author of each chapter was a research collaborator of Roberto Tempo's. This volume is structured in three parts. The first covers robustness and includes topics like time-invariant uncertainties, robust static output feedback design, and the uncertainty quartet. The second part is focused on randomization and probabilistic methods, which covers topics such as compressive sensing, and stochastic optimization. Finally, the third part deals with distributed systems and algorithms, and explores matters involving mathematical sociology, fault diagnoses, and PageRank computation. Each chapter presents exposition, provides new results, and identifies fruitful future directions in research. This book will serve as a valuable reference volume to researchers interested in uncertainty, complexity,

robustness, optimization, algorithms, and networked systems.

Flight Test System

Identification - Roger Larsson
2019-05-15

With the demand for more advanced fighter aircraft, relying on unstable flight mechanical characteristics to gain flight performance, more focus has been put on model-based system engineering to help with the design work. The flight control system design is one important part that relies on this modeling. Therefore, it has become more important to develop flight mechanical models that are highly accurate in the whole flight envelope. For today's modern fighter aircraft, the basic flight mechanical characteristics change between linear and nonlinear as well as stable and unstable as an effect of the desired capability of advanced maneuvering at subsonic, transonic and supersonic speeds. This thesis combines the subject of system identification, which is the art of building mathematical

models of dynamical systems based on measurements, with aeronautical engineering in order to find methods for identifying flight mechanical characteristics. Here, some challenging aeronautical identification problems, estimating model parameters from flight-testing, are treated. Two aspects are considered. The first is online identification during flight-testing with the intent to aid the engineers in the analysis process when looking at the flight mechanical characteristics. This will also ensure that enough information is available in the resulting test data for post-flight analysis. Here, a frequency domain method is used. An existing method has been developed further by including an Instrumental Variable approach to take care of noisy data including atmospheric turbulence and by a sensor-fusion step to handle varying excitation during an experiment. The method treats linear systems that can be both stable and unstable working under feedback control. An

experiment has been performed on a radio-controlled demonstrator aircraft. For this, multisine input signals have been designed and the results show that it is possible to perform more time-efficient flight-testing compared with standard input signals. The other aspect is post-flight identification of nonlinear characteristics. Here the properties of a parameterized observer approach, using a prediction-error method, are investigated. This approach is compared with four other methods for some test cases. It is shown that this parameterized observer approach is the most robust one with respect to noise disturbances and initial offsets. Another attractive property is that no user parameters have to be tuned by the engineers in order to get the best performance. All methods in this thesis have been validated on simulated data where the system is known, and have also been tested on real flight test data. Both of the investigated

approaches show promising results.

Control and Nonlinearity - Jean-Michel Coron 2007

This book presents methods to study the controllability and the stabilization of nonlinear control systems in finite and infinite dimensions. The emphasis is put on specific phenomena due to nonlinearities. In particular, many examples are given where nonlinearities turn out to be essential to get controllability or stabilization. Various methods are presented to study the controllability or to construct stabilizing feedback laws. The power of these methods is illustrated by numerous examples coming from such areas as celestial mechanics, fluid mechanics, and quantum mechanics. The book is addressed to graduate students in mathematics or control theory, and to mathematicians or engineers with an interest in nonlinear control systems governed by ordinary or partial differential equations.

Networked Control Systems -

Alberto Bemporad 2010-10-14
This book finds its origin in the WIDE PhD School on Networked Control Systems, which we organized in July 2009 in Siena, Italy. Having gathered experts on all the aspects of networked control systems, it was a small step to go from the summer school to the book, certainly given the enthusiasm of the lecturers at the school. We felt that a book collecting overview on the important developments and open problems in the field of networked control systems could stimulate and support future research in this appealing area. Given the tremendous current interests in distributed control exploiting wired and wireless communication networks, the time seemed to be right for the book that lies now in front of you. The goal of the book is to set out the core techniques and tools that are available for the modeling, analysis and design of networked control systems. Roughly speaking, the book consists of three parts. The first part presents architectures for

distributed control systems and models of wired and wireless communication networks. In particular, in the first chapter important technological and architectural aspects on distributed control systems are discussed. The second chapter provides insight in the behavior of communication channels in terms of delays, packet loss and information constraints leading to suitable modeling paradigms for communication networks.

Optimal State Estimation - Dan Simon 2006-06-19

A bottom-up approach that enables readers to master and apply the latest techniques in state estimation. This book offers the best mathematical approaches to estimating the state of a general system. The author presents state estimation theory clearly and rigorously, providing the right amount of advanced material, recent research results, and references to enable the reader to apply state estimation techniques confidently across a variety of fields in science and engineering. While there are

other textbooks that treat state estimation, this one offers special features and a unique perspective and pedagogical approach that speed learning: * Straightforward, bottom-up approach begins with basic concepts and then builds step by step to more advanced topics for a clear understanding of state estimation * Simple examples and problems that require only paper and pen to solve lead to an intuitive understanding of how theory works in practice * MATLAB(r)-based source code that corresponds to examples in the book, available on the author's Web site, enables readers to recreate results and experiment with other simulation setups and parameters Armed with a solid foundation in the basics, readers are presented with a careful treatment of advanced topics, including unscented filtering, high order nonlinear filtering, particle filtering, constrained state estimation, reduced order filtering, robust Kalman filtering, and mixed Kalman/H_∞ filtering. Problems

at the end of each chapter include both written exercises and computer exercises. Written exercises focus on improving the reader's understanding of theory and key concepts, whereas computer exercises help readers apply theory to problems similar to ones they are likely to encounter in industry. With its expert blend of theory and practice, coupled with its presentation of recent research results, Optimal State Estimation is strongly recommended for undergraduate and graduate-level courses in optimal control and state estimation theory. It also serves as a reference for engineers and science professionals across a wide array of industries.

Robot Motion Planning and Control - Jean-Paul Laumond
2014-03-12

How can a robot decide what motions to perform in order to achieve tasks in the physical world? Robot motion planning encompasses several different disciplines, most notably robotics, computer science,

control theory and mathematics. This volume presents an interdisciplinary account of recent developments in the field. Topics covered include: combining geometric algorithms and control techniques to account for the nonholonomic constraints of most mobile robots; the mathematical machinery necessary for understanding nonholonomic systems; applying optimal techniques to compute optimal paths; feedback control for nonholonomic mobile robots; probabilistic algorithms and new motion planning approaches; and a survey of recent techniques for dealing with collision detection.

Nonlinear and Adaptive Control Design - Miroslav Krstic 1995-06-14

Using a pedagogical style along with detailed proofs and illustrative examples, this book opens a view to the largely unexplored area of nonlinear systems with uncertainties. The focus is on adaptive nonlinear control results introduced with

the new recursive design methodology--adaptive backstepping. Describes basic tools for nonadaptive backstepping design with state and output feedbacks.

Sliding Mode Control and Observation - Yuri Shtessel
2013-06-01

The sliding mode control methodology has proven effective in dealing with complex dynamical systems affected by disturbances, uncertainties and unmodeled dynamics. Robust control technology based on this methodology has been applied to many real-world problems, especially in the areas of aerospace control, electric power systems, electromechanical systems, and robotics. Sliding Mode Control and Observation represents the first textbook that starts with classical sliding mode control techniques and progresses toward newly developed higher-order sliding mode control and observation algorithms and their applications. The present volume addresses a range of

sliding mode control issues, including: *Conventional sliding mode controller and observer design *Second-order sliding mode controllers and differentiators *Frequency domain analysis of conventional and second-order sliding mode controllers *Higher-order sliding mode controllers and differentiators *Higher-order sliding mode observers *Sliding mode disturbance observer based control *Numerous applications, including reusable launch vehicle and satellite formation control, blood glucose regulation, and car steering control are used as case studies Sliding Mode Control and Observation is aimed at graduate students with a basic knowledge of classical control theory and some knowledge of state-space methods and nonlinear systems, while being of interest to a wider audience of graduate students in electrical/mechanical/aerospace engineering and applied mathematics, as well as researchers in electrical,

computer, chemical, civil, mechanical, aeronautical, and industrial engineering, applied mathematicians, control engineers, and physicists. Sliding Mode Control and Observation provides the necessary tools for graduate students, researchers and engineers to robustly control complex and uncertain nonlinear dynamical systems. Exercises provided at the end of each chapter make this an ideal text for an advanced course taught in control theory. [Nonlinear Dynamical Systems with Self-Excited and Hidden Attractors](#) - Viet-Thanh Pham 2018-02-26

This book highlights the latest findings on nonlinear dynamical systems including two types of attractors: self-excited and hidden attractors. Further, it presents both theoretical and practical approaches to investigating nonlinear dynamical systems with self-excited and hidden attractors. The book includes 20 chapters contributed by respected experts, which focus on various applications such as

biological systems, memristor-based systems, fractional-order systems, finance systems, business cycles, oscillators, coupled systems, hyperchaotic systems, flexible robot manipulators, electronic circuits, and control models. Special attention is given to modeling, design, circuit realization, and practical applications to address recent research problems in nonlinear dynamical systems. The book provides a valuable reference guide to nonlinear dynamical systems for engineers, researchers, and graduate students, especially those whose work involves mechanics, electrical engineering, and control systems.

Block-oriented Nonlinear System Identification -

Fouad Giri 2010-08-18

Block-oriented Nonlinear System Identification deals with an area of research that has been very active since the turn of the millennium. The book makes a pedagogical and cohesive presentation of the methods developed in that

time. These include: iterative and over-parameterization techniques; stochastic and frequency approaches; support-vector-machine, subspace, and separable-least-squares methods; blind identification method; bounded-error method; and decoupling inputs approach. The identification methods are presented by authors who have either invented them or contributed significantly to their development. All the important issues e.g., input design, persistent excitation, and consistency analysis, are discussed. The practical relevance of block-oriented models is illustrated through biomedical/physiological system modelling. The book will be of major interest to all those who are concerned with nonlinear system identification whatever their activity areas. This is particularly the case for educators in electrical, mechanical, chemical and biomedical engineering and for practising engineers in process, aeronautic, aerospace, robotics and vehicles control.

Block-oriented Nonlinear System Identification serves as a reference for active researchers, new comers, industrial and education practitioners and graduate students alike.

Adaptive Control of Parabolic PDEs - Andrey Smyshlyaev 2010-07-01

This book introduces a comprehensive methodology for adaptive control design of parabolic partial differential equations with unknown functional parameters, including reaction-convection-diffusion systems ubiquitous in chemical, thermal, biomedical, aerospace, and energy systems. Andrey Smyshlyaev and Miroslav Krstic develop explicit feedback laws that do not require real-time solution of Riccati or other algebraic operator-valued equations. The book emphasizes stabilization by boundary control and using boundary sensing for unstable PDE systems with an infinite relative degree. The book also presents a rich collection of methods for system identification of PDEs, methods

that employ Lyapunov, passivity, observer-based, swapping-based, gradient, and least-squares tools and parameterizations, among others. Including a wealth of stimulating ideas and providing the mathematical and control-systems background needed to follow the designs and proofs, the book will be of great use to students and researchers in mathematics, engineering, and physics. It also makes a valuable supplemental text for graduate courses on distributed parameter systems and adaptive control.

Nonlinear and Optimal Control Theory - Andrei A. Agrachev 2008-06-24

The lectures gathered in this volume present some of the different aspects of Mathematical Control Theory. Adopting the point of view of Geometric Control Theory and of Nonlinear Control Theory, the lectures focus on some aspects of the Optimization and Control of nonlinear, not necessarily smooth, dynamical systems. Specifically, three of the five lectures discuss

respectively: logic-based switching control, sliding mode control and the input to the state stability paradigm for the control and stability of nonlinear systems. The remaining two lectures are devoted to Optimal Control: one investigates the connections between Optimal Control Theory, Dynamical Systems and Differential Geometry, while the second presents a very general version, in a non-smooth context, of the Pontryagin Maximum Principle. The arguments of the whole volume are self-contained and are directed to everyone working in Control Theory. They offer a sound presentation of the methods employed in the control and optimization of nonlinear dynamical systems.

Iterative Learning Control for Flexible Structures -

Tingting Meng 2020-03-23

This book presents iterative learning control (ILC) to address practical issues of flexible structures. It is divided into four parts: Part I provides a general introduction to ILC

and flexible structures, while Part II proposes various types of ILC for simple flexible structures to address issues such as vibration, input saturation, input dead-zone, input backlash, external disturbances, and trajectory tracking. It also includes simple partial differential equations to deal with the common problems of flexible structures. Part III discusses the design of ILC for flexible micro aerial vehicles and two-link manipulators, and lastly, Part IV offers a summary of the topics covered. Unlike most of the literature on ILC, which focuses on ordinary differential equation systems, this book explores distributed parameter systems, which are comparatively less stabilized through ILC. Including a comprehensive introduction to ILC of flexible structures, it also examines novel approaches used in ILC to address input constraints and disturbance rejection. This book is intended for researchers, graduate students and engineers in various fields,

such as flexible structures, external disturbances, nonlinear inputs and tracking control.

Foundations of Computational Mathematics - DeVore Iserles Suli 2001-05-17

Collection of papers by leading researchers in computational mathematics, suitable for graduate students and researchers.

Adaptive Backstepping Control of Uncertain Systems - Jing Zhou 2008-02-07

This book employs the powerful and popular adaptive backstepping control technology to design controllers for dynamic uncertain systems with non-smooth nonlinearities. Various cases including systems with time-varying parameters, multi-inputs and multi-outputs, backlash, dead-zone, hysteresis and saturation are considered in design and analysis. For multi-inputs and multi-outputs systems, both centralized and decentralized controls are addressed. This book not only presents recent research

results including theoretical success and practical development such as the proof of system stability and the improvement of system tracking and transient performance, but also gives self-contained coverage of fundamentals on the backstepping approach illustrated with simple examples. Detail description of methodologies for the construction of adaptive laws, feedback control laws and associated Lyapunov functions is systematically provided in each case. Approaches used for the analysis of system stability and tracking and transient performances are elaborated. Two case studies are presented to show how the presented theories are applied.

Differentially Flat Systems - Hebertt Sira-Ramírez 2018-10-03

Illustrating the power, simplicity, and generality of the concept of flatness, this reference explains how to identify, utilize, and apply flatness in system planning and design. The book includes a

large assortment of exercises and models that range from elementary to complex classes of systems. Leading students and professionals through a vast array of designs, simulations, and analytical studies on the traditional uses of flatness, Differentially Flat Systems contains an extensive amount of examples that showcase the value of flatness in system design, demonstrate how flatness can be assessed in the context of perturbed systems and apply static and dynamic feedback controller design techniques.

Fuzzy Differential Equations and Applications for Engineers and Scientists

S. Chakraverty 2016-11-25

Differential equations play a vital role in the modeling of physical and engineering problems, such as those in solid and fluid mechanics, viscoelasticity, biology, physics, and many other areas. In general, the parameters, variables and initial conditions within a model are considered as being defined exactly. In reality there may be only

vague, imprecise or incomplete information about the variables and parameters available. This can result from errors in measurement, observation, or experimental data; application of different operating conditions; or maintenance induced errors. To overcome uncertainties or lack of precision, one can use a fuzzy environment in parameters, variables and initial conditions in place of exact (fixed) ones, by turning general differential equations into Fuzzy Differential Equations ("FDEs"). In real applications it can be complicated to obtain exact solution of fuzzy differential equations due to complexities in fuzzy arithmetic, creating the need for use of reliable and efficient numerical techniques in the solution of fuzzy differential equations. These include fuzzy ordinary and partial, fuzzy linear and nonlinear, and fuzzy arbitrary order differential equations. This unique work provides a new direction for the reader in the use of basic concepts of fuzzy

differential equations, solutions and its applications. It can serve as an essential reference work for students, scholars, practitioners, researchers and academicians in engineering and science who need to model uncertain physical problems.

Fractional Order Control and Synchronization of Chaotic Systems - Ahmad Taher Azar
2017-02-27

The book reports on the latest advances in and applications of fractional order control and synchronization of chaotic systems, explaining the concepts involved in a clear, matter-of-fact style. It consists of 30 original contributions written by eminent scientists and active researchers in the field that address theories, methods and applications in a number of research areas related to fractional order control and synchronization of chaotic systems, such as: fractional chaotic systems, hyperchaotic systems, complex

systems, fractional order discrete chaotic systems, chaos control, chaos synchronization, jerk circuits, fractional chaotic systems with hidden attractors, neural network, fuzzy logic controllers, behavioral modeling, robust and adaptive control, sliding mode control, different types of synchronization, circuit realization of chaotic systems, etc. In addition to providing readers extensive information on chaos fundamentals, fractional calculus, fractional differential equations, fractional control and stability, the book also discusses key applications of fractional order chaotic systems, as well as multidisciplinary solutions developed via control modeling. As such, it offers the perfect reference guide for graduate students, researchers and practitioners in the areas of fractional order control systems and fractional order chaotic systems.